Machine Learning from Weak Supervision: An Empirical Risk Minimization Approach



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What Is This Lecture about? ²

- Machine learning from big labeled data has been highly successful.
 - Speech recognition, image understanding, natural language translation, recommendation, ...

- However, there are various applications where massive labeled data is not available.
 - Medicine, disaster, robots, brain, ...



What Is This Lecture about? ³

- There are many approaches to coping with the label-cost problem:
 - Improve data collection (e.g., crowdsourcing)
 - Use a simulator to generate pseudo data
 - Use domain knowledge (i.e., engineering)
 - Use cheap but weak data (e.g., unlabeled)

Disclaimer:

- There are many great works on weakly supervised learning.
- Coverage of this lecture is biased and limited.

Binary Supervised Classification⁴



- Larger amount of labeled data yields better classification accuracy.
- Estimation error of the boundary ¹³ decreases in order $1/\sqrt{n}$.

n : Number of labeled samples

0.1

400

300

500

600

700

Unsupervised Classification ⁵

Gathering labeled data is costly. Let's use unlabeled data that are often cheap to collect:



- Unsupervised classification is typically clustering.
- This works well only when each cluster corresponds to a class.

Semi-Supervised Classification ⁶

Chapelle, Schölkopf & Zien (MIT Press 2006) and many

- Use a large number of unlabeled samples and a small number of labeled samples.
- Find a boundary along the cluster structure induced by unlabeled samples:
 - Sometimes very useful.
 - But not that different from unsupervised classification.



Classification of Classification ⁷



Textbook

Machine Learning from Weak Supervision

An Empirical Risk Minimization Approach



Masashi Sugiyama, Han Bao, Takashi Ishida, Nan Lu, Tomoya Sakai, and Gang Niu Masashi Sugiyama, Han Bao, Takashi Ishida, Nan Lu, Tomoya Sakai, Gang Niu. Machine Learning from Weak Supervision: **An Empirical Risk** Minimization Approach, 320 pages, MIT Press, 2022.

PU Classification

du Plessis, Niu & Sugiyama (NIPS2014, ICML2015) Niu, du Plessis, Sakai, Ma & Sugiyama (NIPS2016) Kiryo, Niu, du Plessis & Sugiyama (NIPS2017)

- Only PU data is available; N data is missing:
 - Click vs. non-click
 - Friend vs. non-friend

From PU data, PN classifiers are trainable!

Pconf Classification

Ishida, Niu & Sugiyama (NeurIPS2018)

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Only P data is available, not U data:

- Data from rival companies cannot be obtained.
- Only positive results are reported (publication bias).
- "Only-P learning" is unsupervised.

From Pconf data, PN classifiers are trainable!



UU Classification

du Plessis, Niu & Sugiyama (TAAI2013) Nan, Niu, Menon & Sugiyama (ICLR2019)

From two sets of unlabeled data with different class priors, PN classifiers are trainable!



SDU Classification

Bao, Niu & Sugiyama (ICML2018)

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Delicate classification (money, religion...):

- Highly hesitant to directly answer questions.
- Less reluctant to just say "same as him/her".
- From SU data, PN classifiers are trainable!



- Learning from DU data is also possible.
- Learning from SDU data is also possible.

Shimada, Bao, Sato & Sugiyama (NeCo2021)

Multiclass Methods

Class 1

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Class 2

Boundary

Labeling patterns in multi-class problems is extremely painful.

- Complementary labels: Specify a class that
 Specify a class that
 a pattern does not belong to ("not 1").
- Partial labels: Feng, Kaneko, Han, Niu, An & Sugiyama (ICML2020) Feng, Lv, Han, Xu, Niu, Geng, An & Sugiyama (NeurIPS2020)
 Specify a subset of classes that contains the correct one ("1 or 2").
- Single-class confidence: Cao, Feng, Shu, Xu, An, Niu & Sugiyama (arXiv2021)
 One-class data with full confidence
 ("1 with 60%, 2 with 30%, and 3 with 10%")



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- P: Positive
- N: Negative
- U: Unlabeled
- Conf: Confidence
- S: Similar
- D: Dissimilar
- Comp: Complementary

PN Classification ¹⁵ (Ordinary Supervised Classification) Labeled data: $\{(x_i, y_i)\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} p(x, y)$

- Input $x \in \mathbb{R}^d$: d-dimensional real vector
- Output $y \in \{+1, -1\}$: Binary class label



Some Definitions

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Classifier: $f : \mathbb{R}^d \to \mathbb{R}$

• Label prediction by $\widehat{y} = \operatorname{sign}(f(x))$ (e.g., linear, additive, kernel, deep models).

■ Margin:
$$m = yf(x)$$

• $m > 0 \implies sign(f(x)) = y$
• $m < 0 \implies sign(f(x)) \neq y$
■ Classification is correct.

Zero-one loss: $\ell_{0/1}(m) = \frac{1}{2} (1 - \operatorname{sign}(m))$

- 0 for correct prediction.
- 1 for wrong prediction.

 $R_{0/1}(f) = \mathbb{E}_{p(\boldsymbol{x},y)} \left[\ell_{0/1} \left(yf(\boldsymbol{x}) \right) \right] \qquad \ell_{0/1}(m) = \frac{1}{2} \left(1 - \text{sign}(m) \right)$

• Our goal: Find a minimizer of $R_{0/1}(f)$.

But this is impossible since p(x, y) is unknown:

• Let's use samples: $\{(\boldsymbol{x}_i, y_i)\}_{i=1}^n \overset{\text{i.i.d.}}{\sim} p(\boldsymbol{x}, y)$

i.i.d.: Independent and identically distributed

• Empirical approximation:

$$\widehat{R}_{0/1}(f) = \frac{1}{n} \sum_{i=1}^{n} \ell_{0/1} \Big(y_i f(\boldsymbol{x}_i) \Big)$$

$$= R_{0/1}(f) + O_p\left(\frac{1}{\sqrt{n}}\right)$$

Minimization of Empirical Classification Error

$$\widehat{R}_{0/1}(f) = \frac{1}{n} \sum_{i=1}^{n} \ell_{0/1} \Big(y_i f(\boldsymbol{x}_i) \Big)$$

- However, minimization of $\widehat{R}_{0/1}(f)$ is NP-hard, due to discrete nature of $\ell_{0/1}$:
 - We may not be able to obtain a global minimizer in practice.

Let's use a smoother loss!

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Surrogate Loss

Let's use a smoother loss as a surrogate:



PN Empirical Risk Minimization²⁰

Classification risk for loss ℓ :

$$R(f) = \mathbb{E}_{p(\boldsymbol{x},y)} \Big[\ell \Big(y f(\boldsymbol{x}) \Big) \Big]$$

Empirical risk:

• Expectation is approximated by sample average:

$$\widehat{R}_{\text{PN}}(f) = \frac{1}{n} \sum_{i=1}^{n} \ell\left(y_i f(\boldsymbol{x}_i)\right) = R(f) + O_p\left(\frac{1}{\sqrt{n}}\right)$$
$$\{(\boldsymbol{x}_i, y_i)\}_{i=1}^{n} \stackrel{\text{i.i.d.}}{\sim} p(\boldsymbol{x}, y)$$

• Minimize it within a certain model class (e.g., linear, additive, kernel, deep,...):

$$\widehat{f}_{\rm PN} = \operatorname*{argmin}_{f} \widehat{R}_{\rm PN}(f)$$



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PU Classification: Setup

 $\{\boldsymbol{x}_{i}^{\mathrm{P}}\}_{i=1}^{n_{\mathrm{P}}} \overset{\text{i.i.d.}}{\sim} p(\boldsymbol{x}|y=+1)$

Given: Positive and unlabeled samples

 $\{x_i^U\}_{i=1}^{n_U} \stackrel{\text{i.i.d.}}{\sim} p(x)$ Goal: Obtain a PN classifier

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the risk cannot be directly estimated.

PU Risk Estimation

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$$R(f) = \pi \mathbb{E}_{p(\boldsymbol{x}|y=+1)} \left[\ell \left(f(\boldsymbol{x}) \right) \right] + (1-\pi) \mathbb{E}_{p(\boldsymbol{x}|y=-1)} \left[\ell \left(-f(\boldsymbol{x}) \right) \right]$$

U-density is a mixture of P- and N-densities:

$$p(\mathbf{x}) = \pi p(\mathbf{x}|y = +1) + (1 - \pi)p(\mathbf{x}|y = -1)$$



PU Risk Estimation (cont.) ²⁵

du Plessis, Niu & Sugiyama (ICML2015)

$$R(f) = \pi \mathbb{E}_{p(\boldsymbol{x}|\boldsymbol{y}=+1)} \left[\ell \left(f(\boldsymbol{x}) \right) \right] + (1-\pi) \mathbb{E}_{\boldsymbol{p}(\boldsymbol{x}|\boldsymbol{y}=-1)} \left[\ell \left(-f(\boldsymbol{x}) \right) \right]$$
$$p(\boldsymbol{x}) = \pi p(\boldsymbol{x}|\boldsymbol{y}=+1) + (1-\pi)p(\boldsymbol{x}|\boldsymbol{y}=-1)$$

This allow us to eliminate the N-density: $(1 - \pi)p(\boldsymbol{x}|\boldsymbol{y} = -1) = p(\boldsymbol{x}) - \pi p(\boldsymbol{x}|\boldsymbol{y} = +1)$ $R(f) = \pi \mathbb{E}_{p(\boldsymbol{x}|\boldsymbol{y}=+1)} \left[\ell \left(f(\boldsymbol{x}) \right) \right]$ $+ \mathbb{E}_{p(\boldsymbol{x})} \left[\ell \left(- f(\boldsymbol{x}) \right) \right] - \pi \mathbb{E}_{p(\boldsymbol{x}|\boldsymbol{y}=+1)} \left[\ell \left(- f(\boldsymbol{x}) \right) \right]$

 Unbiased risk estimation is possible from PU data, just by replacing expectations by sample averages! **PU Empirical Risk Minimization**²⁶ $R(f) = \pi \mathbb{E}_{p(\boldsymbol{x}|\boldsymbol{y}=+1)} \left[\ell \left(f(\boldsymbol{x}) \right) \right] + \mathbb{E}_{p(\boldsymbol{x})} \left[\ell \left(- f(\boldsymbol{x}) \right) \right] - \pi \mathbb{E}_{p(\boldsymbol{x}|\boldsymbol{y}=+1)} \left[\ell \left(- f(\boldsymbol{x}) \right) \right]$

Replacing expectations by sample averages gives an empirical risk:

$$\begin{split} \widehat{R}_{\mathrm{PU}}(f) &= \frac{\pi}{n_{\mathrm{P}}} \sum_{i=1}^{n_{\mathrm{P}}} \ell\Big(f(\boldsymbol{x}_{i}^{\mathrm{P}})\Big) + \frac{1}{n_{\mathrm{U}}} \sum_{i=1}^{n_{\mathrm{U}}} \ell\Big(-f(\boldsymbol{x}_{i}^{\mathrm{U}})\Big) - \frac{\pi}{n_{\mathrm{P}}} \sum_{i=1}^{n_{\mathrm{P}}} \ell\Big(-f(\boldsymbol{x}_{i}^{\mathrm{P}})\Big) \\ &\{\boldsymbol{x}_{i}^{\mathrm{P}}\}_{i=1}^{n_{\mathrm{P}}} \stackrel{\text{i.i.d.}}{\sim} p(\boldsymbol{x}|\boldsymbol{y}=+1) \quad \{\boldsymbol{x}_{i}^{\mathrm{U}}\}_{i=1}^{n_{\mathrm{U}}} \stackrel{\text{i.i.d.}}{\sim} p(\boldsymbol{x}) \end{split}$$

Optimal convergence rate is attained:

Niu, du Plessis, Sakai, Ma & Sugiyama (NIPS2016)

$$R(\hat{f}_{\rm PU}) - R(f^*) \le C(\delta) \left(\frac{2\pi}{\sqrt{n_{\rm P}}} + \frac{1}{\sqrt{n_{\rm U}}}\right)$$

with probability $1 - \delta$

 $\widehat{f}_{\rm PU} = \operatorname{argmin}_{f} \widehat{R}_{\rm PU}(f)$ $f^* = \operatorname{argmin}_{f} R(f)$

 $n_{
m P}, n_{
m U}$: # of P, U samples

Theoretical Comparison with PN²⁷

Niu, du Plessis, Sakai, Ma & Sugiyama (NIPS2016)

Estimation error bounds for PU and PN:

 $\hat{f}_{\rm PN} = \operatorname{argmin} \hat{R}_{\rm PN}(f)$

$$R(\widehat{f}_{\rm PU}) - R(f^*) \le C(\delta) \left(\frac{2\pi}{\sqrt{n_{\rm P}}} + \frac{1}{\sqrt{n_{\rm U}}}\right)$$
$$R(\widehat{f}_{\rm PN}) - R(f^*) \le C(\delta) \left(\frac{\pi}{\sqrt{n_{\rm P}}} + \frac{1-\pi}{\sqrt{n_{\rm N}}}\right)$$

with probability $1 - \delta$

 $\widehat{R}_{PN}(f) = \frac{1}{n} \sum_{i=1}^{n} \ell\left(y_i f(\boldsymbol{x}_i)\right) \qquad n_P, n_N, n_U: \text{# of P, N, U samples}$

Comparison: PU bound is smaller than PN if

$$\frac{\pi}{\sqrt{n_{\rm P}}} + \frac{1}{\sqrt{n_{\rm U}}} < \frac{1-\pi}{\sqrt{n_{\rm N}}}$$

PU can be better than PN, provided many PU data!

Further Correction

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$$R(f) = \pi \mathbb{E}_{p(\boldsymbol{x}|\boldsymbol{y}=+1)} \left[\ell \left(f(\boldsymbol{x}) \right) \right] + (1-\pi) \mathbb{E}_{\boldsymbol{p}(\boldsymbol{x}|\boldsymbol{y}=-1)} \left[\ell \left(-f(\boldsymbol{x}) \right) \right]$$

Risk for P data
Risk for N data $R^{-}(f)$

PU formulation: $p(\boldsymbol{x}) = \pi p(\boldsymbol{x}|\boldsymbol{y} = +1) + (1 - \pi)p(\boldsymbol{x}|\boldsymbol{y} = -1)$ $R^{-}(f) = \mathbb{E}_{\boldsymbol{p}(\boldsymbol{x})} \left[\ell \left(-f(\boldsymbol{x}) \right) \right] - \pi \mathbb{E}_{\boldsymbol{p}(\boldsymbol{x}|\boldsymbol{y}=+1)} \left[\ell \left(-f(\boldsymbol{x}) \right) \right]$

• If $\ell(m) \ge 0, \ \forall m$, $R^-(f) \ge 0$.

 However, its PU empirical approximation can be negative due to "difference of approximations".

$$\widehat{R}_{\mathrm{PU}}^{-}(f) = \frac{1}{n_{\mathrm{U}}} \sum_{i=1}^{n_{\mathrm{U}}} \ell \left(-f(\boldsymbol{x}_{i}^{\mathrm{U}}) \right) - \frac{\pi}{n_{\mathrm{P}}} \sum_{i=1}^{n_{\mathrm{P}}} \ell \left(-f(\boldsymbol{x}_{i}^{\mathrm{P}}) \right) \geq 0$$

 This problem is more critical for flexible models such as deep nets.

Non-Negative PU Classification²⁹



We constrain the sample approximation term to be non-negative through back-prop training:

$$\widetilde{R}_{\mathrm{PU}}(f) = \frac{\pi}{n_{\mathrm{P}}} \sum_{i=1}^{n_{\mathrm{P}}} \ell\Big(f(\boldsymbol{x}_{i}^{\mathrm{P}})\Big) + \max\left\{\boldsymbol{0}, \ \frac{1}{n_{\mathrm{U}}} \sum_{i=1}^{n_{\mathrm{U}}} \ell\Big(-f(\boldsymbol{x}_{i}^{\mathrm{U}})\Big) - \frac{\pi}{n_{\mathrm{P}}} \sum_{i=1}^{n_{\mathrm{P}}} \ell\Big(-f(\boldsymbol{x}_{i}^{\mathrm{P}})\Big)\right\}$$

• Now the risk estimator is biased. Is it really good?

Theoretical Analysis

Kiryo, Niu, du Plessis & Sugiyama (NIPS2017)

Absolute function ReLU function

Generalized Leaky ReLU

$$\widetilde{R}_{\mathrm{PU}}(f) = \frac{\pi}{n_{\mathrm{P}}} \sum_{i=1}^{n_{\mathrm{P}}} \ell\Big(f(\boldsymbol{x}_{i}^{\mathrm{P}})\Big) + \max\left\{0, \ \frac{1}{n_{\mathrm{U}}} \sum_{i=1}^{n_{\mathrm{U}}} \ell\Big(-f(\boldsymbol{x}_{i}^{\mathrm{U}})\Big) - \frac{\pi}{n_{\mathrm{P}}} \sum_{i=1}^{n_{\mathrm{P}}} \ell\Big(-f(\boldsymbol{x}_{i}^{\mathrm{P}})\Big)\right\}$$

- $\widetilde{R}_{PU}(f)$ is still consistent and its bias decreases exponentially: $\mathcal{O}(e^{-n_{\rm P}-n_{\rm U}})$ $n_{\rm P}, n_{\rm U}$: # of P, U samples
 - In practice, we can ignore the bias of $\widetilde{R}_{PU}(f)$!
- Mean-squared error of $\widetilde{R}_{PU}(f)$ is not more than the original one.
 - In practice, $\widetilde{R}_{PU}(f)$ is more reliable!
- **Risk of** $\operatorname{argmin}_{f} \widetilde{R}_{PU}(f)$ for linear models attains • Learned function is optimal. $\mathcal{O}_p\left(\frac{1}{\sqrt{n_{\mathrm{P}}}} + \frac{1}{\sqrt{n_{\mathrm{U}}}}\right)$
- Extension to leaky-ReLU: Lu, Zhang, Niu & Sugiyama (AISTATS2020)
 - Corresponding to gradient ascent.

Signal Enhancement

Ito & Sugiyama (ICASSP2023)

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 \rightarrow Do not generalize well in reality.

Proposed method: Use non-parallel noisy signal and noise.

		Methods	SI-SNRi [dB]
Non-parallel	ſ	Proposed	14.62 (0.20)
	1	MixIT ^{Wisdom+} (NeurIPS2020)	12.19 (4.50)
Parallel	\rightarrow	Supervised	15.86 (1.28)





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Pconf Classification: Setup ³³

Ishida, Niu & Sugiyama (NeurIPS2018)

Given: Positive-confidence samples

• Positive patterns: $\{\boldsymbol{x}_i\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} p(\boldsymbol{x}|y=+1)$

 $\{(\boldsymbol{x}_{i}, r_{i})\}_{i=1}^{n}$

• Their confidence: $r_i = P(y = +1 | \boldsymbol{x}_i)$

Goal: Obtain a PN classifier



Pconf Risk Estimation

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Classification risk: $R(f) = \mathbb{E}_{p(\boldsymbol{x},y)} \left[\ell \left(yf(\boldsymbol{x}) \right) \right]$

Naïve "confidence-weighting" is not correct. $R(f) \neq \mathbb{E}_{p(\boldsymbol{x}|y=+1)} \Big[r(\boldsymbol{x}) \ell \Big(f(\boldsymbol{x}) \Big) + (1 - r(\boldsymbol{x})) \ell \Big(- f(\boldsymbol{x}) \Big) \Big]$ $r(\boldsymbol{x}) = P(y = +1|\boldsymbol{x})$

Correct form is given by importance sampling:

$$R(f) = \pi \mathbb{E}_{p(\boldsymbol{x}|y=+1)} \left[\ell \left(f(\boldsymbol{x}) \right) + \frac{1 - r(\boldsymbol{x})}{r(\boldsymbol{x})} \ell \left(- f(\boldsymbol{x}) \right) \right]$$

resulting in an empirical risk:

$$\widehat{R}_{\text{Pconf}}(f) \propto \sum_{i=1}^{n} \left[\ell \left(f(\boldsymbol{x}_{i}) \right) + \frac{1 - r_{i}}{r_{i}} \ell \left(- f(\boldsymbol{x}_{i}) \right) \right]$$
$$\{\boldsymbol{x}_{i}\}_{i=1}^{n} \stackrel{\text{i.i.d.}}{\sim} p(\boldsymbol{x}|\boldsymbol{y} = +1) \quad r_{i} = P(\boldsymbol{y} = +1|\boldsymbol{x}_{i})$$



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UU Classification: Setup

du Plessis, Niu & Sugiyama (TAAI2013) Lu, Niu, Menon & Sugiyama (ICLR2019) Lu, Zhang, Niu & Sugiyama (AISTATS2020)

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Given: Two sets of unlabeled data

 $\{x_i\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} p(x) \ \{x'_i\}_{i=1}^{n'} \stackrel{\text{i.i.d.}}{\sim} p'(x)$ = Assumption: Only class-priors are different $p(y) \neq p'(y) \qquad p(x|y) = p'(x|y)$ = Goal: Obtain a PN classifier



Optimal UU Classifier

du Plessis, Niu & Sugiyama (TAAI2013)

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Boundary

Sign of the difference of class-posteriors:

$$g(\boldsymbol{x}) = \operatorname{sign}[p(y = +1|\boldsymbol{x}) - p(y = -1|\boldsymbol{x})]$$

Under uniform test class-prior,

$$g(\boldsymbol{x}) = C \operatorname{sign}[p(\boldsymbol{x}) - p'(\boldsymbol{x})]$$
$$C = \operatorname{sign}[p(y = +1) - p'(y = +1)]$$

Sign of *C* is unknown, but just knowing sign[p(x) - p'(x)]still allows optimal separation!

UU Risk Estimation

Lu, Niu, Menon & Sugiyama (ICLR2019)

For

- uniform test class-prior: $\pi = 1/2$
- symmetric loss: $\ell(m) + \ell(-m) = \text{Const.}$

the classification risk can be expressed as

$$R(f) = \mathbb{E}_{p(\boldsymbol{x},y)} \left[\ell \left(yf(\boldsymbol{x}) \right) \right]$$

$$\propto \mathbb{E}_{p(\boldsymbol{x})} \left[\ell \left(f(\boldsymbol{x}) \right) \right] + \mathbb{E}_{p'(\boldsymbol{x}')} \left[\ell \left(-f(\boldsymbol{x}') \right) \right] + \text{Const.}$$
Soluting an empirical risk (up to label flip):

resulting an empirical risk (up to label flip):

$$\widehat{R}_{\text{UU}}(f) \propto \frac{1}{n} \sum_{i=1}^{n} \ell\left(f(\boldsymbol{x}_{i})\right) + \frac{1}{n'} \sum_{i=1}^{n'} \ell\left(-f(\boldsymbol{x}_{i}')\right)$$

$$\{\boldsymbol{x}_i\}_{i=1}^n \stackrel{\text{i.i.d.}}{\sim} p(\boldsymbol{x}) \ \{\boldsymbol{x}'_i\}_{i=1}^{n'} \stackrel{\text{i.i.d.}}{\sim} p'(\boldsymbol{x})$$

Extension to UUU...

 $m \ (\geq 2)$

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- U^m classification: $m \cup sets \{x_i^{(j)}\}_{i=1,j=1}^{n_j,m}$ are given.
- Apply UU for pairs of U sets: Scott & Zhang (NeurIPS2020)
 - However, it is computationally expensive.
- Surrogate set classification:

Lu, Lei, Niu, Sato & Sugiyama (ICML2021)

• Learn an m-class classifier f(x) that probabilistically assigns the dataset ID to each sample.

 $\{x_{i}^{(j)}, \bar{y}_{i}^{(j)} = j\}_{i=1, j=1}^{n_{j}, m}$ $p(\bar{y}|x) \approx f(x)$

 It can be deterministically converted to the classifier that assigns PN labels to each sample.

 $oldsymbol{p}(y|oldsymbol{x}) pprox oldsymbol{T}(oldsymbol{f}(oldsymbol{x}))$



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SU Classification

Bao, Niu & Sugiyama (ICML2018)

Given: Similar and unlabeled samples

$$\{ (\boldsymbol{x}_i, \boldsymbol{x}'_i) \}_{i=1}^{n_{\mathrm{S}}} \stackrel{\text{i.i.d.}}{\sim} p(\boldsymbol{x}, \boldsymbol{x}' | y = y') \\ \{ \boldsymbol{x}_i^{\mathrm{U}} \}_{i=1}^{n_{\mathrm{U}}} \stackrel{\text{i.i.d.}}{\sim} p(\boldsymbol{x})$$



Goal: Obtain a PN classifier

This is a special case of UU classification:

$$p(y = +1) = \frac{\pi^2}{2\pi^2 - 2\pi + 1}$$
$$p'(y = +1) = \pi$$

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Extensions to DU/SD/SDU 42

Shimada, Bao, Sato & Sugiyama (NeCo2021)

- DU and SD classification are also special cases of UU classification:
 - DU: p(y = +1) = 1/2 $p'(y = +1) = \pi$



• SD:
$$p(y = +1) = \pi^2/(2\pi^2 - 2\pi + 1)$$

 $p'(y = +1) = 1/2$

SDU classification is also possible by combining DU/SU/SD classification (in the same way as PNU classification).

Further Extensions

Noisy SD: Two types of noise:

- Pairing corruption noise: Pairwise labels (S/D) are noisy.
- Labeling corruption noise: Latent class labels (P/N) are noisy.

Similar-confidence (Sconf):

• Similar pairs with confidence. $p(\boldsymbol{x}, \boldsymbol{x}'|y = y')$

Pairwise confidence comparison:

• Sample pairs with one having larger An & Sugiyama (ICML2021) Pconf than the other. p(y=+1|x) > p(y=+1|x')

Confidence difference:

$$(x, x') = p(y = +1|x) - p(y = +1|x')$$





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Dan, Bao & Sugiyama

Cao, Feng, Xu, An, Niu & Sugiyama (ICML2021) $, oldsymbol{x'}|y=y')$



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Complementary Labels

Ishida, Niu, Hu & Sugiyama (NIPS2017) Ishida, Niu, Menon & Sugiyama (ICML2019)

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- Labeling patterns in multi-class problems:
 - Selecting a correct class from a long list of candidate classes is extremely painful.
- Complementary labels:
 - Specify a class that a pattern does not belong to.
 - This is much easier and faster to perform!
- From complementary labels, classifiers are trainable! 1/1



Complementary Classification ⁴⁶

Given: Complementarily labeled data

$$\{(\boldsymbol{x}_i, \bar{y}_i)\}_{i=1}^n \overset{\text{i.i.d.}}{\sim} \bar{p}(\boldsymbol{x}, \bar{y}) \quad \bar{p}(\boldsymbol{x}, \bar{y}) = \frac{1}{c-1} \sum_{y \neq \bar{y}} p(\boldsymbol{x}, y)$$

• Pattern x does not belong to class $\overline{y} \in \{1, 2, \dots, c\}$. Goal: Obtain a multiclass classifier



Multi-Class Classification 47

C-class classifier: $f(x) = \underset{y \in \{1,...,c\}}{\operatorname{argmax}} g_y(x)$

 $g_y(oldsymbol{x})$: one-vs-rest classifier for y

C-class loss: L(y, g(x))

$$oldsymbol{g}(oldsymbol{x}) = (g_1(oldsymbol{x}), \dots, g_c(oldsymbol{x}))^ op$$

• One-versus-rest:

$$L_{\text{OVR}}\left(y, \boldsymbol{g}(\boldsymbol{x})\right) = \ell\left(g_{y}(\boldsymbol{x})\right) + \frac{1}{c-1}\sum_{y'\neq y}\ell\left(-g_{y'}(\boldsymbol{x})\right)$$

• Pairwise comparison:

$$L_{\mathrm{PC}}\left(y, \boldsymbol{g}(\boldsymbol{x})
ight) = \sum_{y' \neq y} \ell\left(g_y(\boldsymbol{x}) - g_{y'}(\boldsymbol{x})
ight)$$

c-class classification risk:

$$R(\boldsymbol{g}) = \mathbb{E}_{p(\boldsymbol{x},y)} \Big[L\Big(y, \boldsymbol{g}(\boldsymbol{x})\Big) \Big]$$

Complementary Risk Estimation⁴⁸

Ishida, Niu, Menon & Sugiyama (ICML2019)

 $\{(\boldsymbol{x}_i, \bar{y}_i)\}_{i=1}^n \overset{\text{i.i.d.}}{\sim} \bar{p}(\boldsymbol{x}, \bar{y})$

$$R(\boldsymbol{g}) = \mathbb{E}_{p(\boldsymbol{x},y)} \Big[L\Big(y, \boldsymbol{g}(\boldsymbol{x})\Big) \Big]$$

Risk can be equivalently expressed as $R(\boldsymbol{g}) = \mathbb{E}_{\bar{\boldsymbol{p}}(\boldsymbol{x}, \bar{\boldsymbol{y}})} \left[\bar{L} \left(\bar{\boldsymbol{y}}, \boldsymbol{g}(\boldsymbol{x}) \right) \right]$

• Complementary loss:

$$\bar{L}\left(\bar{y}, \boldsymbol{g}(\boldsymbol{x})\right) = -(c-1)L\left(\bar{y}, \boldsymbol{g}(\boldsymbol{x})\right) + \sum_{y=1}^{c} L\left(y, \boldsymbol{g}(\boldsymbol{x})\right)$$

Empirical risk estimation is possible from complementary data!

$$\widehat{R}_{\text{Comp}}(\boldsymbol{g}) = \frac{1}{n} \sum_{i=1}^{n} \overline{L}(\overline{y}_i, \boldsymbol{g}(\boldsymbol{x}_i))$$

Generalizations

From unbiased risk estimation to surrogate complementary loss:

- Surrogate approximation later.
- Multiple complementary labels (=partial labels): $\bar{p}(x, \bar{Y}) = \sum_{k=1}^{k-1} p(x, \bar{Y})$
 - Consider the size of complementary sets.

$$\begin{split} \boldsymbol{x}, \bar{Y}) &= \sum_{j=1}^{k-1} p(s=j) \bar{p}(\boldsymbol{x}, \bar{Y} \mid s=j) \\ \bar{p}(\boldsymbol{x}, \bar{Y} \mid s=j) &:= \begin{cases} \frac{1}{\binom{k-1}{j}} \sum_{y \notin \bar{Y}} p(\boldsymbol{x}, y), & \text{if } |\bar{Y}| = j, \\ 0, & \text{otherwise.} \end{cases} \end{split}$$

Release from the uniform assumption:

• Selected completely at random.

Wang, Ishida, Zhang, Niu & Sugiyama (arXiv2023)

$$p(k \in \overline{Y} | \boldsymbol{x}, k \in \mathcal{Y} \setminus \{y\}) = p(k \in \overline{Y} | k \in \mathcal{Y} \setminus \{y\}) = c_k$$



Chou, Niu, G., Lin &

Sugiyama (ICML2020)



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- P: Positive
- N: Negative
- U: Unlabeled
- Conf: Confidence
- S: Similar
- D: Dissimilar
- Comp: Complementary

Empirical Risk Minimization Framework ⁵¹ for Weakly Supervised Learning

Any loss, classifier, regularizer, and optimizer can be used.



Towards More Reliable ML

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Reliability for expectable situations:

- Model the corruption process explicitly and correct the solution.
 - How to handle modeling error?
- Reliability for unexpected situations:
 - Consider worst-case robustness ("min-max").
 - How to make it less conservative?
 - Include human support ("rejection").
 - How to handle real-time applications?
- Exploring somewhere in the middle would be practically more useful:
 - Use partial knowledge of the corruption process.