

# Recent Advances in Robust Machine Learning

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東京大学  
THE UNIVERSITY OF TOKYO



# About Myself

## ■ My jobs:

- Director: RIKEN AIP
- Professor: University of Tokyo
- Consultant: several local startups



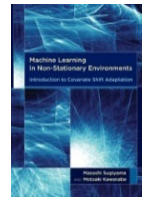
## ■ Interests: Machine learning (ML)

- Weakly-supervised learning,
- Robust learning,
- Transfer learning,
- Density ratio estimation,
- Reinforcement learning,
- Variational inference...

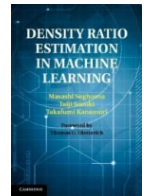
## ■ Academic activities:

- Program Chairs for NeurIPS2015, AISTATS2019, ACML2010/2020...

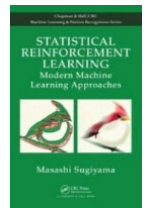
Sugiyama & Kawanabe, **Machine Learning in Non-Stationary Environments**, MIT Press, 2012



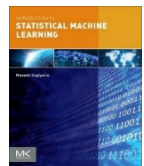
Sugiyama, Suzuki & Kanamori, **Density Ratio Estimation in Machine Learning**, Cambridge University Press, 2012



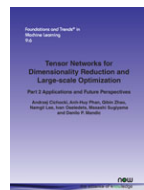
Sugiyama, **Statistical Reinforcement Learning**, Chapman and Hall/CRC, 2015



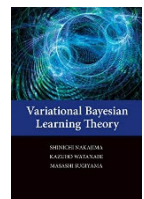
Sugiyama, **Introduction to Statistical Machine Learning**, Morgan Kaufmann, 2015



Cichocki, Phan, Zhao, Lee, Oseledets, Sugiyama & Mandic, **Tensor Networks for Dimensionality Reduction and Large-Scale Optimizations**, Now, 2017

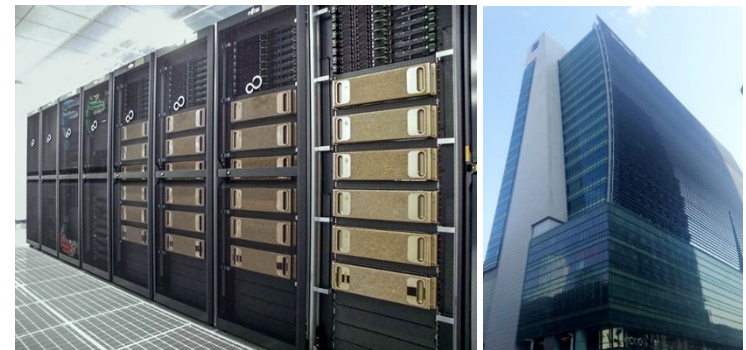
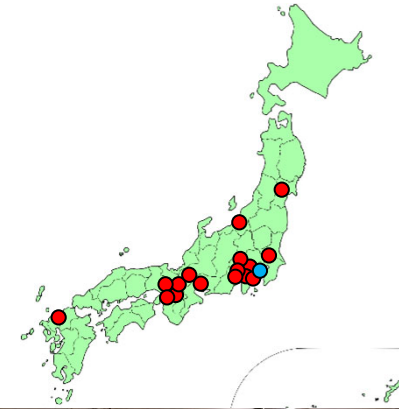


Nakajima, Watanabe & Sugiyama, **Variational Bayesian Learning Theory**, Cambridge University Press, 2019



# RIKEN Center for Advanced Intelligence Project (AIP)

- 10-year national project in Japan (2016-2025):
  - **Develop next-generation AI technology**  
(learning and optimization theory, etc.)
  - **Accelerate scientific research**  
(material, cancer, stem cells, genomics, etc.)
  - **Solve socially critical problems**  
(natural disaster, elderly healthcare, etc.)
  - **Study of ethical, legal and social issues of AI**  
(ethical guideline, privacy protection, etc.)
  - **Human resource development**  
(150+ researchers, 200+ students,  
150+ interns, 300+ visiting scientists,  
40+ industry projects)



# Today's Topic:

## Robust Machine Learning

- In real-world applications, it becomes increasingly important to consider **robustness**:
  - **Noise**: sensor error, human error
  - **Insufficient information**: weak supervision
  - **Bias**: sample selection bias, changing environments
  - **Attack**: adversarial noise, distribution shift
- In this talk, I will give an overview of our recent advances in robust machine learning.

<http://www.ms.k.u-tokyo.ac.jp/sugi/publications.html>



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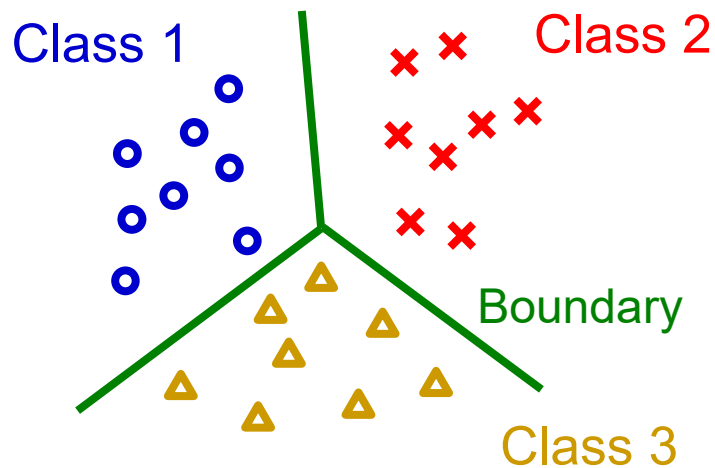
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1. Noisy label learning
2. Weakly supervised learning
3. Transfer learning
4. Adversarial learning
5. Future outlook

# Ordinary Classification

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- Clean training data:  $\{(\mathbf{x}_i, y_i)\}_{i=1}^n$



$\mathbf{x} \in \mathbb{R}^d$  : Input pattern

$y \in \{1, \dots, c\}$  : Clean class label  
(not necessarily separable)

- Training error minimization is statistically consistent and work well:

$$\frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{g}(\mathbf{x}_i))$$

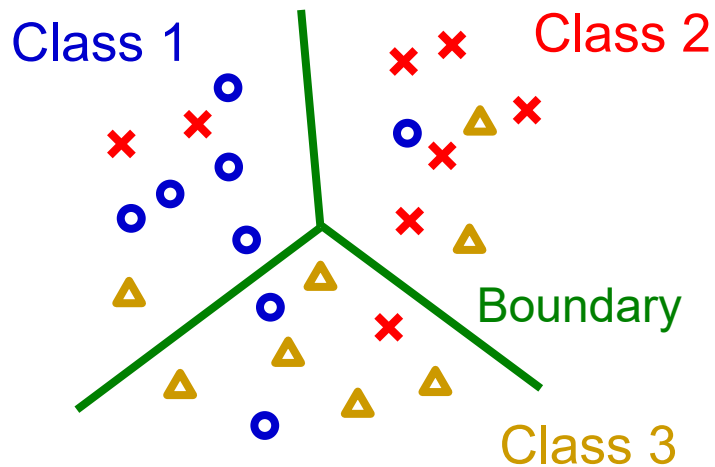
$\mathbf{g}(\mathbf{x}) \in \mathbb{R}^c$  : Classifier

$\ell(y, \mathbf{g}(\mathbf{x})) \in \mathbb{R}$  : Loss

# Noisy Classification

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- Noisy training data:  $\{(\mathbf{x}_i, \tilde{y}_i)\}_{i=1}^n$



$\mathbf{x} \in \mathbb{R}^d$ : Input pattern

$\tilde{y} \in \{1, \dots, c\}$ : Noisy class label  
(clean labels are corrupted)

- Training error minimization is no longer consistent and does not work well:

$$\frac{1}{n} \sum_{i=1}^n \ell(\tilde{y}_i, g(\mathbf{x}_i))$$

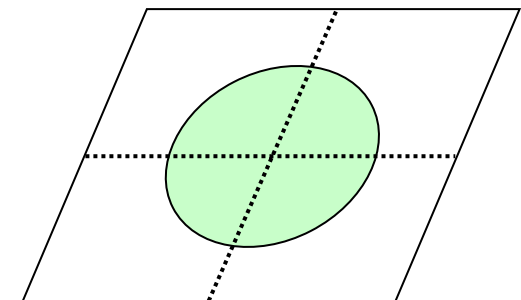
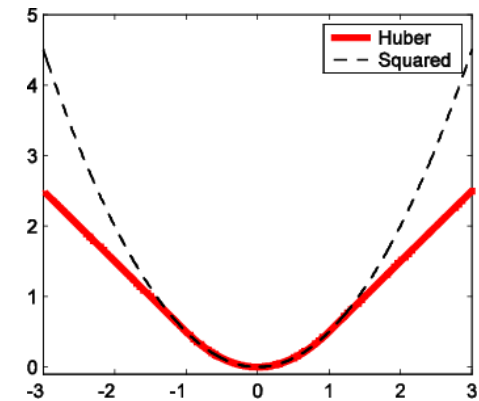
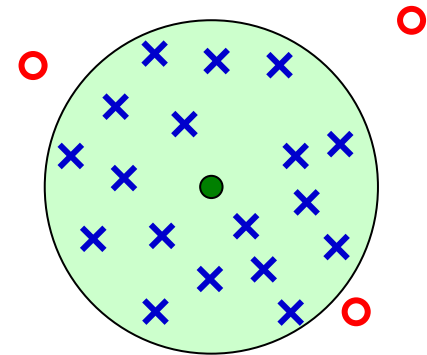
$g(\mathbf{x}) \in \mathbb{R}^c$ : Classifier

$\ell(y, g(\mathbf{x})) \in \mathbb{R}$ : Loss

# Standard Approaches

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- **Unsupervised outlier removal:**
  - Substantially difficult
- **Robust loss, regularization:**
  - Not robust enough
- We want to go beyond the limitations of existing approaches!
  - Noise transition correction
  - Noiseless sample selection
  - Model capacity control





# (1-1) Noise Transition Correction 9

## ■ Noise transition matrix $T$ :

- Flipping probability from  $y$  to  $\tilde{y}$ .

$$T^{\top} = \begin{array}{c|cc} & y & \tilde{y} \\ \hline \tilde{y} & 1 & 0.1 & 0.5 \\ & 0 & 0.8 & 0.5 \\ & 0 & 0.1 & 0 \end{array}$$

## ■ Major approaches: Patrini et al. (CVPR2017)

- **Loss correction** by  $T^{-1}$  to eliminate noise.
- **Classifier correction** by  $T^{\top}$  to simulate noise.

## ■ We want to estimate $T$ **only from noisy data**:

- Use human cognition as a “mask” for  $T$ .

Han, Yao, Niu, Zhou, Tsang, Zhang & Sugiyama (NeurIPS2018)

- Learn  $T$  and a classifier simultaneously.

Xia, Liu, Wang, Han, Gong, Niu & Sugiyama (NeurIPS2019)

- Decompose  $T$  into simpler components.

Yao, Liu, Han, Gong, Deng, Niu, Sugiyama & Tao (NeurIPS2020)

- Extension to input-dependent noise  $T(x)$ .

Xia, Liu, Han, Wang, Gong, Liu, Niu, Tao & Sugiyama (NeurIPS2020)

# (1-2) Co-teaching

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## ■ Memorization of neural nets:

Arpit et al. (ICML2017)  
Zhang et al. (ICLR2017)

- Stochastic gradient descent fits clean data faster.
- However, naïve early stopping does not work well.

## ■ “Co-teaching” between two neural nets:

- Teach small-loss data each other.

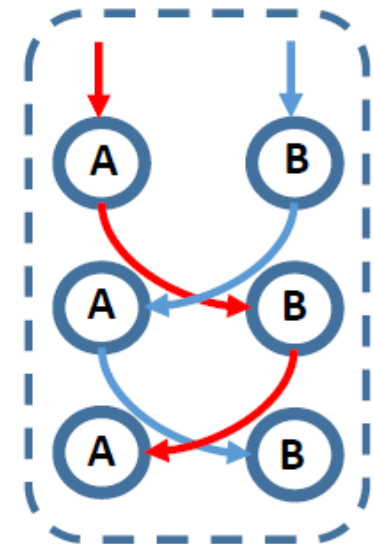
Han, Yao, Yu, Niu, Xu, Hu, Tsang & Sugiyama (NeurIPS2018)

- Teach only disagreed data.

Yu, Han, Yao, Niu, Tsang & Sugiyama (ICML2019)

- Gradient ascent for large-loss data.

Han, Niu, Yu, Yao, Xu, Tsang & Sugiyama (ICML2020)



## ■ No theory but very robust in experiments:

- Works well even if 50% labels are randomly flipped.

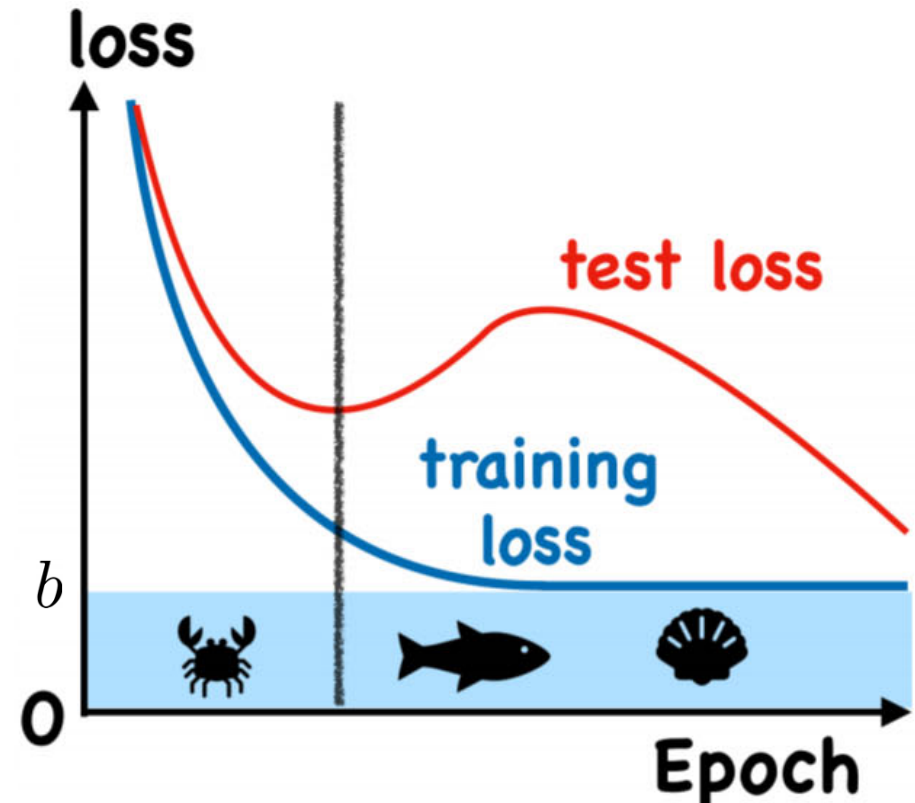
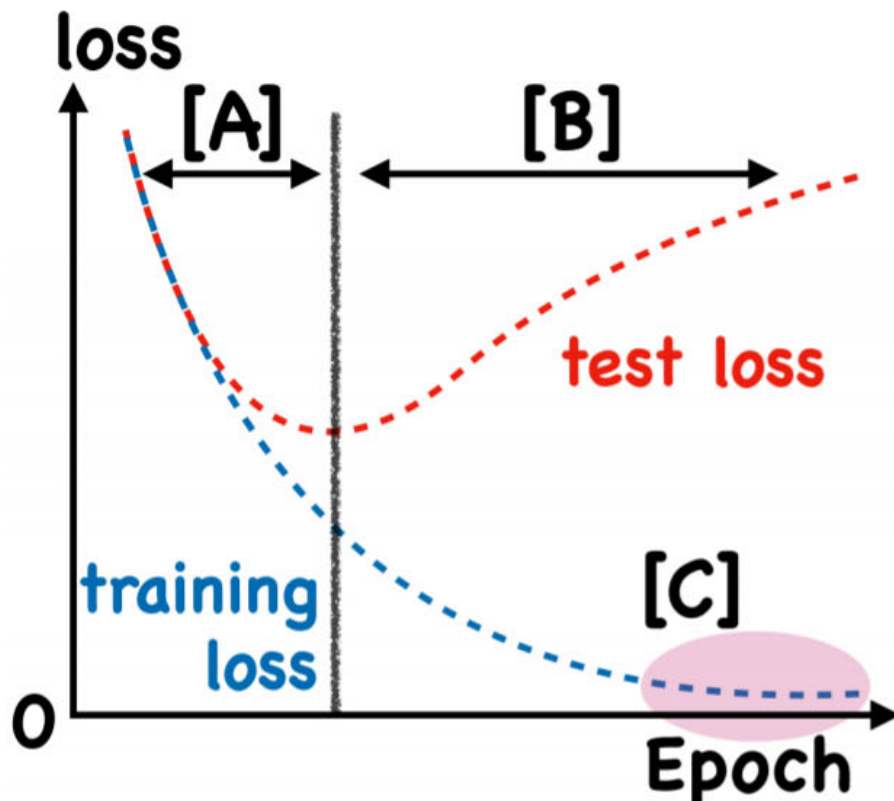
# (1-3) Flooding

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- Neural nets tend to overfit.
- “Flooding” the training error prevents overfitting.
  - It induces double descent?

$$|R(f) - b| + b$$

Ishida, Yamane, Sakai, Niu & Sugiyama (ICML2020)





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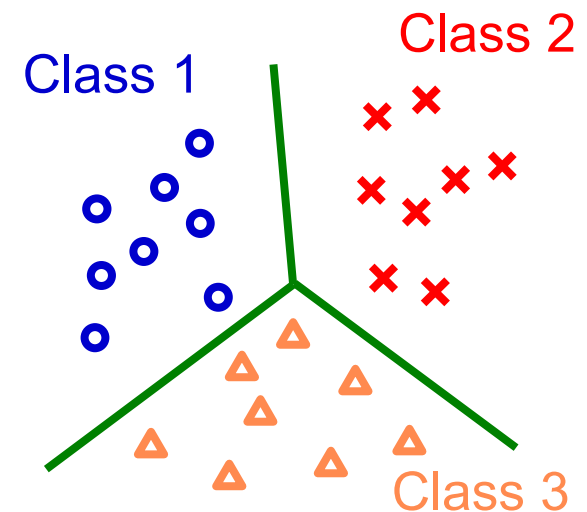
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1. Noisy label learning
2. **Weakly supervised learning**
3. Transfer learning
4. Adversarial learning
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# Weakly Supervised Learning

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- Ordinary supervised learning requires **fully labeled data** (input-output pairs).
- But collecting fully labeled data can be expensive in practice.
- Can we utilize **“weakly” labeled data**?
  - Complementary classification
  - Partial-label classification
  - Various weakly supervised classification methods for binary problems



# (2-1) Complementary Classification <sup>14</sup>

## ■ Complementary label:

a class the pattern does not belong to.

- E.g., “not class 1”, “not a cat”.
- Cheaper than ordinary labels.

## ■ Classifiers can be trained only from complementary labels.

### ● Unbiased risk estimation

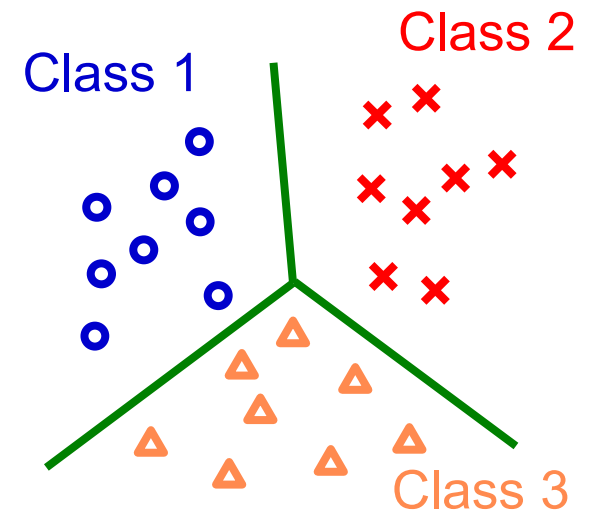
Ishida, Niu & Sugiyama (NIPS2017)  
Ishida, Niu, Menon & Sugiyama (ICML2019)

### ● Multiple complementary labels

Feng, Kaneko, Han, Niu, An & Sugiyama (ICML2020)

### ● Beyond unbiased risk estimation

Chou, Niu, Lin & Sugiyama (ICML2020)



$$1/\sqrt{n}$$

# (2-2) Partial-Label Classification <sup>15</sup>

## ■ Partial label: Nguyen and Caruana (KDD2008)

a subset of labels containing the true one

- E.g., “Either 1 or 2”, “dog or cat”
- Cheaper than ordinary labels

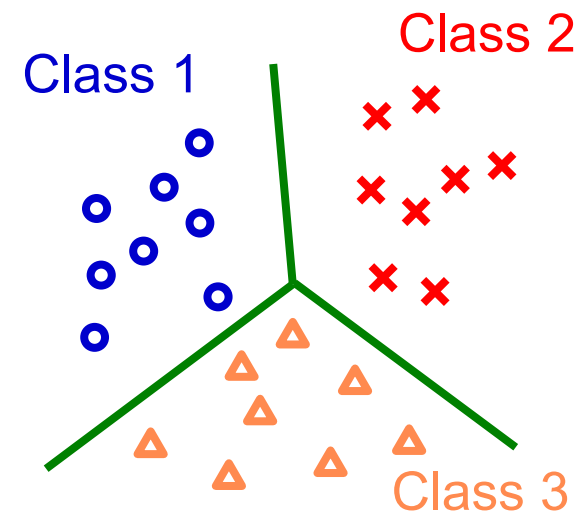
## ■ Classifiers can be trained only from partial labels. $1/\sqrt{n}$

- Progressive identification of correct labels.

Lv, Xu, Feng, Niu, Geng & Sugiyama (ICML2020)

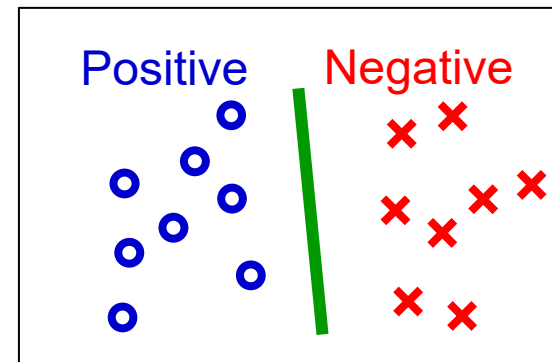
- Explicit modeling of partial label generation.

Feng, Lv, Han, Xu, Niu, Geng, An & Sugiyama (NeurIPS2020)



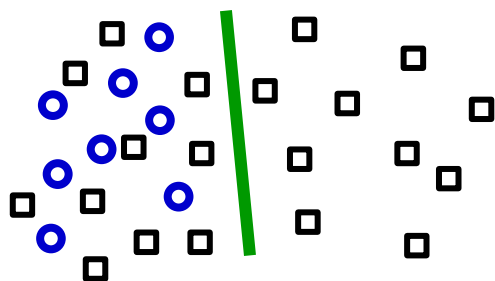
# (2-3) More for Binary Problems

Binary classification is possible only from weakly supervised data!



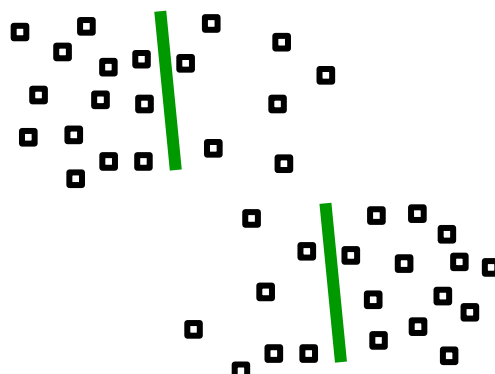
$$1/\sqrt{n}$$

Positive-Unlabeled



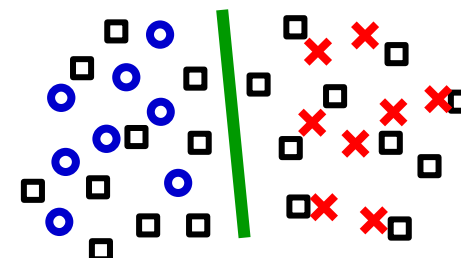
du Plessis, Niu & Sugiyama (NIPS2014, ICML2015)  
 Niu, du Plessis, Sakai, Ma & Sugiyama (NIPS2016)  
 Kiryo, du Plessis, Niu & Sugiyama (NIPS2017)  
 Hsieh, Niu & Sugiyama (ICML2019)

Unlabeled-Unlabeled



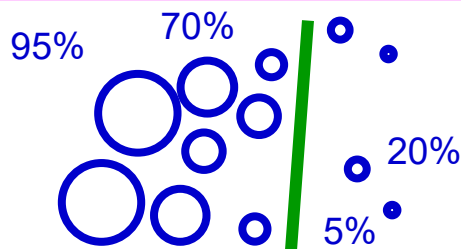
du Plessis, Niu & Sugiyama (TAAI2013)  
 Lu, Niu, Menon & Sugiyama (ICLR2019)  
 Charoenphakdee, Lee & Sugiyama (ICML2019)  
 Lu, Zhang, Niu & Sugiyama (AISTATS2020)

Positive-Negative-Unlabeled



Sakai, du Plessis, Niu & Sugiyama (ICML2017)  
 Sakai, Niu & Sugiyama (MLJ2018)

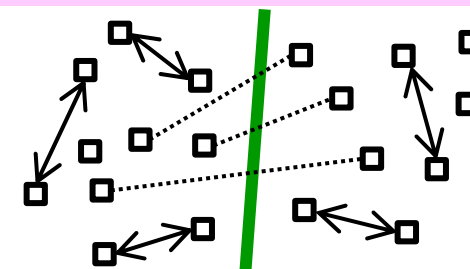
Positive confidence



Ishida, Niu & Sugiyama (NeurIPS2018)

Sugiyama, Sakai, Ishida, Nan, Bao & Niu,  
 Machine Learning from Weak Supervision,  
 MIT Press, 2021?

Similar-Dissimilar-Unlabeled



Bao, Niu & Sugiyama (ICML2018)  
 Shimada, Bao, Sato & Sugiyama (arXiv2019)  
 Dan, Bao & Sugiyama (arXiv2020)





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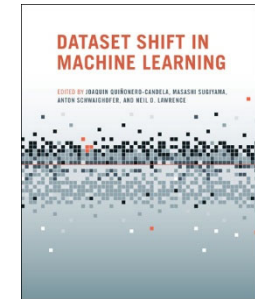
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1. Noisy label learning
2. Weakly supervised learning
3. **Transfer learning**
4. Adversarial learning
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# Transfer Learning

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Quiñero-Candela, Sugiyama, Schwaighofer & Lawrence (MIT Press 2009)



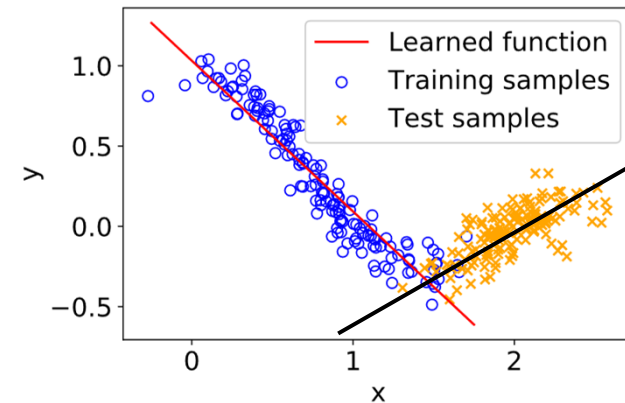
■ Training and test data often have different distributions, due to

- changing environments,
- sample selection bias.

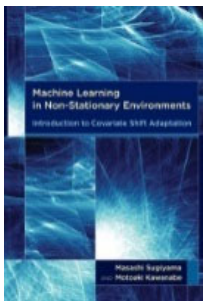
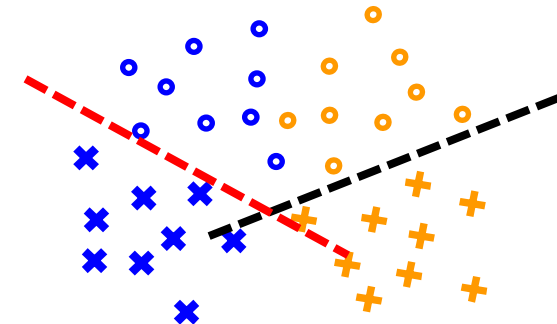
■ **Transfer learning (domain adaptation):**

- Match the distributions so that training data resemble test data.

Regression



Classification



Sugiyama & Kawanabe,  
Machine Learning in Non-Stationary Environments,  
MIT Press, 2012

# Unsupervised Transfer Learning <sup>19</sup>

■ Given training input-output and test input, match the training and test distributions:

- Better discrepancy measures for distribution matching:

Kuroki, Charoenphakdee, Bao, Honda, Sato & Sugiyama (AAAI2019)  
Lee, Charoenphakdee, Kuroki & Sugiyama (arXiv2019)

- Handling noisy labels in the source domain:

Liu, Lu, Han, Niu, Zhang & Sugiyama (arXiv2019)

- No/incomplete unlabeled data from the test domain:

Ishii, Takenouchi & Sugiyama (ACML2019)  
Ishii, Takenouchi & Sugiyama (WACV2020)

- Transferring data generation mechanism:

Teshima, Sato & Sugiyama (ICML2020)  
Teshima, Ishikawa, Tojo, Oono, Ikeda & Sugiyama (NeurIPS2020)

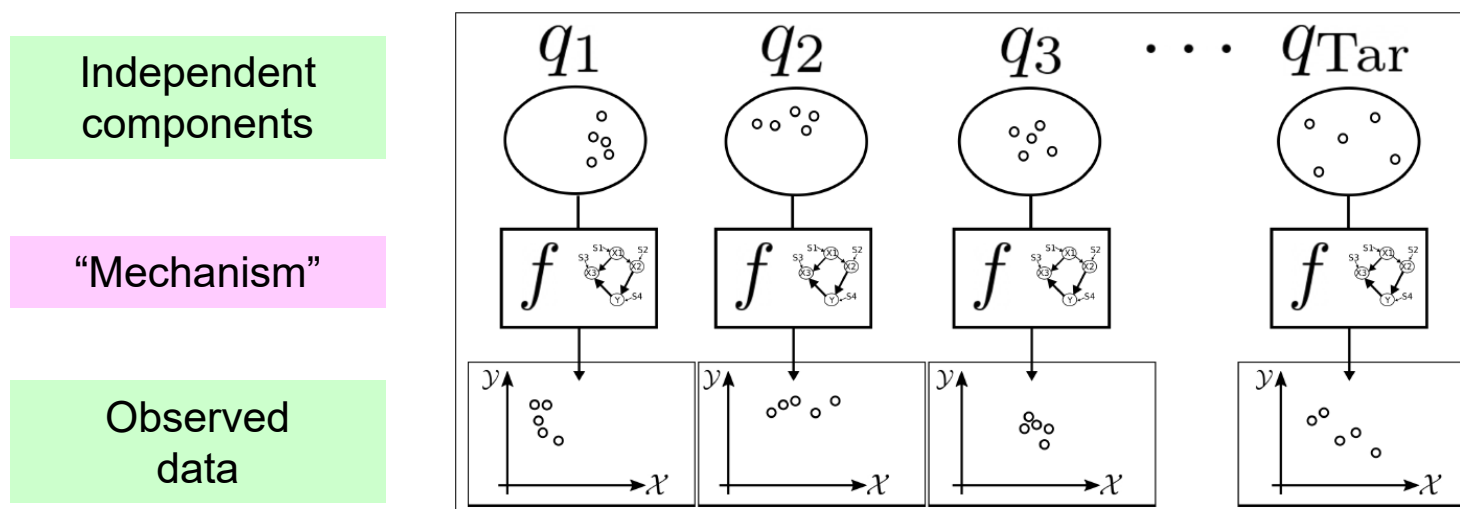
- Simultaneous learning of a classifier and importance weights:

Zhang, Yamane, Lu & Sugiyama (ACML2020)  
Fang, Lu, Niu & Sugiyama (NeurIPS2020)

# (3-1) Mechanism Transfer

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- Is transfer learning possible **when data distributions are seemingly very different?**
- Yes, if **data generation mechanisms** are shared:
  - Use invertible neural networks (INNs) to invert the data generation mechanism. Teshima, Sato & Sugiyama (ICML2020)
  - INNs are **universal approximators**. Teshima, Ishikawa, Tojo, Oono, Ikeda & Sugiyama (NeurIPS2020)



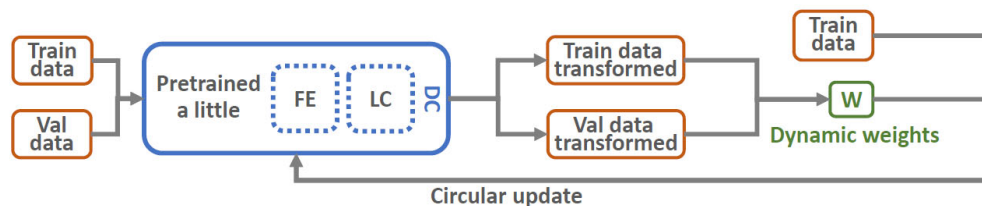
## (3-2) One-Step Adaptation

### Standard approach: 2 steps

- Weight estimation:  $\min_w D(w, p_{te}/p_{tr})$
- Weighted classifier training:  $\min_f \mathbb{E}_{p_{tr}} [w(x, y) \ell(f(x), y)]$

### Proposed methods: 1 step

- With a common feature extractor for  $w$  and  $f$ , learn them **dynamically** in mini-batch training.



Fang, Lu, Niu & Sugiyama (NeurIPS2020)

- Minimize **an upper bound of the risk** w.r.t.  $w$  and  $f$  under covariate shift  $p_{tr}(y|x) = p_{te}(y|x)$ :

Zhang, Yamane, Lu & Sugiyama (ACML2020)

$$\min_{w, f} J(w, f) \quad J(w, f) \geq R^2(f)$$



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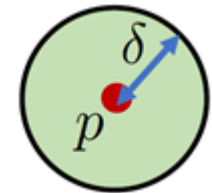
1. Noisy label learning
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# Adversarial Change in Test Input

- An adversary changes test input points to confuse our predictor.
  - We want to be robust against such change.
- Various studies of adversarial learning:
  1. Distributionally robust learning.
  2. Adversarial training for pointwise attack.
  3. Rejection of adversarial data.

# (4-1) Distributionally Robust Learning 24

- **Setting**: an adversary changes the test distribution **arbitrarily**.
- **Approach**: Learn a predictor such that it still works well for the **worst** test distribution.



- Well studied in regression (output is continuous) and works well.

$$\min_{\theta} \sup_{q \in \mathcal{Q}_p} \mathbb{E}_{q(x,y)} [\ell(g_{\theta}(x), y)]$$

- In classification (output is categorical), additional condition is needed to enhance the robustness, e.g., **latent prior probability change**.

$$\mathcal{Q}_p = \{q \mid D_f(q||p) \leq \delta\}$$

**“f-divergence ball”**

[Bagnell 2005, Ben-Tal+ 2013, Namkoong+ 2016, 2017]

Hu, Niu, Sato & Sugiyama (ICML2018)

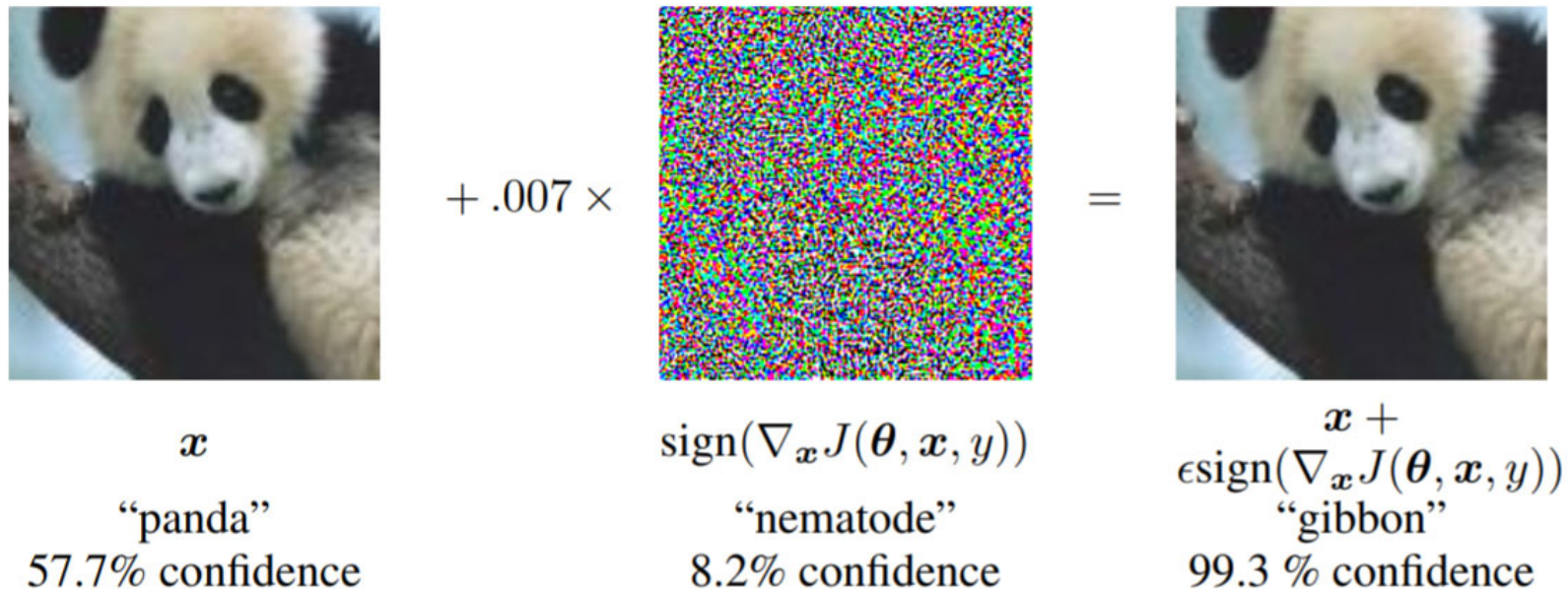
Storkey & Sugiyama (NIPS2007)



## (4-2) Pointwise Attack

- Deep neural networks are vulnerable to **small perturbations** in test input.

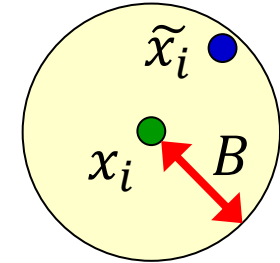
Goodfellow et al. (ICLR2015)



- We want to make deep neural networks stable for such test input perturbations.

# (4-2a) Adversarial Training for Pointwise Attack

- **Setting:** an adversary changes test input points **arbitrarily**.



- **Approach:** Consider the **worst** test input  $\tilde{x}_i$ :

$$\min_f \frac{1}{n} \sum_{i=1}^n \ell(f(\tilde{x}_i), y_i)$$

$$\tilde{x}_i = \arg \max_{\tilde{x} \in B(x_i)} \ell(f(\tilde{x}), y_i)$$

- Conditions for the calibration of surrogate classification loss has been elucidated.

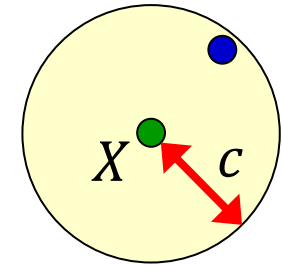
Bao, Scott & Sugiyama  
(COLT2020)

- However,

- There is **no theoretical guarantee** for robustness.
- Minimax training is **too conservative**.

# (4-2b) Guaranteed Defense to Pointwise Attack

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- Stabilize output of the neural net:

$$\forall \epsilon, \left( \|\epsilon\|_2 < c \Rightarrow t_X = \operatorname{argmax}_i \{F(X + \epsilon)_i\} \right)$$

- Lipchitz-margin training:

Tsuzuku, Sato & Sugiyama (NeurIPS2018)

- Compute the Lipchitz constant for the entire network:

$$\|F(X) - F(X + \epsilon)\|_2 \leq L_F \|\epsilon\|_2$$

- Train the neural net to have large prediction margins:

$$\forall i \neq t_X, (F_{t_X} \geq F_i + \sqrt{2}cL_F)$$

- Robustness is theoretically guaranteed.

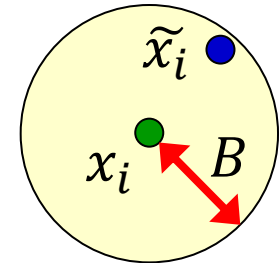
- However, the guarded area is not so large.

# (4-2c) Friendly Adversarial Training <sup>28</sup>

- Minimax training is too conservative:

$$\min_f \frac{1}{n} \sum_{i=1}^n \ell(f(\tilde{x}_i), y_i)$$

$$\tilde{x}_i = \arg \max_{\tilde{x} \in B(x_i)} \ell(f(\tilde{x}), y_i)$$



- “Friendly” adversarial training:

Zhang, Xu, Han, Niu, Cui,  
Sugiyama & Kankanhalli (ICML2020)

- Among adversarial inputs, consider the one with margin  $\rho$ .

$$\tilde{x}_i = \arg \min_{\tilde{x} \in B(x_i)} \ell(f(\tilde{x}), y_i)$$

$$\text{s.t. } \ell(f(\tilde{x}), y_i) - \min_y \ell(f(\tilde{x}), y) \geq \rho$$

- Considering the geometry can further improve the robustness experimentally.
- Theoretical analysis is still open.

Zhang, Zhu, Niu, Han,  
Sugiyama & Kankanhalli (arXiv2020)

## 4-3) Classification with Reject Option 29

- In severe applications, better to **reject** difficult test inputs and ask human to predict instead.
- **Standard approach:** Test points having **low-confidence prediction** are rejected.
  - Logistic loss results in weak performance.
  - New rejection criteria for general losses with guaranteed theoretical convergence and better experimental performance.
- However,
  - Adversarial input gives high-prediction confidence.
  - Not possible to handle real-time applications.

Ni, Charoenphakdee, Honda & Sugiyama (NeurIPS2019)  
Charoenphakdee, Cui, Zhang & Sugiyama (arXiv2020)



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# Summary

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- Nowadays, ML systems are deployed in various societal problems, where **reliability** is extremely important.
- We explored robustness to different factors:
  - **Noise**: sensor error, human error
  - **Insufficient information**: weak supervision
  - **Bias**: sample selection bias, changing environments
  - **Attack**: adversarial noise, distribution shift

# Challenges in Reliable ML

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- **Reliable ML in expectable situations:**
  - Model the corruption process explicitly and correct the solution.
- **Reliable ML in unexpected situations:**
  - Consider worst-case robustness.
  - Include human support.
- **Exploring somewhere in the middle would be practically useful and important.**
  - Partial knowledge of the corruption process.



# Challenges in Reliable ML

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- In reliable ML research, the choice of **performance metrics** is crucial.
  - Simply improving the accuracy is not the goal.
- Since humans use ML systems, performance metrics should reflect **human cognitive bias**.
  - Ex: in image evaluation, MSE is not natural, but we care edges, texture, faces, etc.
- “Designing” appropriate performance metrics is an important challenge.

# Past and Future of AI Research 34

## Logical AI

- 1960's: Inference and search
- 1980's: Expert systems and knowledge bases

## Neuro-inspired AI

- 1960's: Single-layer perceptrons
- 1990's: Multi-layer perceptrons

## Statistical ML based AI

- 2000's: Frequentist statistics, convex optimization, Bayesian statistics
- 2010's: Deep learning

## Future AI

Human-like AI? Human-inclusive AI?

# Thanks to Great Collaborators!

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## The University of Tokyo

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  - [Naoto Yokoya](#) (Complexity, Computer, Information, RIKEN)
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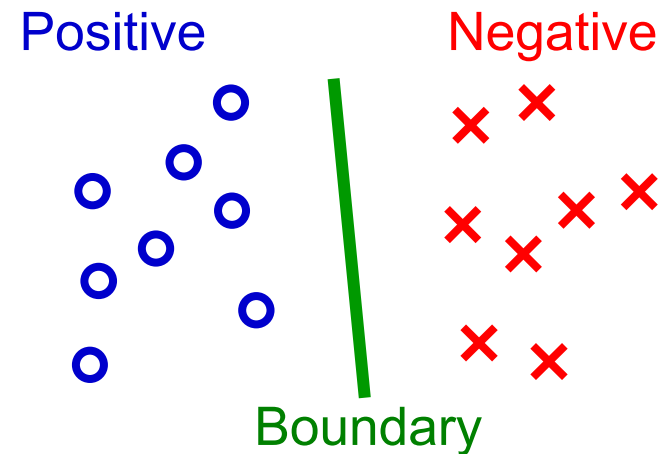
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Junior Research Associate Takeshi Teshima	



# Weakly Supervised Learning

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- Ordinary supervised learning requires **fully labeled data** (input-output pairs).
- But collecting fully labeled data can be expensive in practice.
- Can we utilize **“weakly” labeled data**?
  - No negative data
  - Positive confidence data
  - Similar/dissimilar data
  - Complementary data
  - Partial-label data



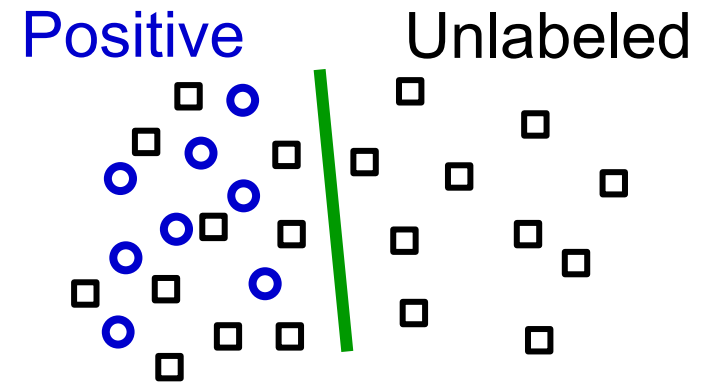
P: Positive, N: Negative, U: Unlabeled

## (2-1) PU Classification

- Only **positive and unlabeled data** is available; negative data is completely missing:

- Click vs. non-click
- Friend vs. non-friend

- We want to minimize the risk of classifier  $f$  only from PU data:



$$\begin{aligned}
 R(f) &= \mathbb{E}_{p(\mathbf{x}, y)} \left[ \ell(y f(\mathbf{x})) \right] \\
 &= \underbrace{\pi \mathbb{E}_{p(\mathbf{x} | y=+1)} \left[ \ell(f(\mathbf{x})) \right]}_{\text{Risk for P data}} + \underbrace{(1 - \pi) \mathbb{E}_{p(\mathbf{x} | y=-1)} \left[ \ell(-f(\mathbf{x})) \right]}_{\text{Risk for N data}}
 \end{aligned}$$

$\pi = p(y = +1)$

- But N-risk cannot be estimated directly.

# Key Trick

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du Plessis, Niu & Sugiyama (NIPS2014, ICML2015)  
Niu, du Plessis, Sakai, Ma & Sugiyama (NIPS2016)  
Kiryo, du Plessis, Niu & Sugiyama (NIPS2017)  
Hsieh, Niu & Sugiyama (ICML2019)

Risk for P data

Risk for N data

$$R(f) = \pi \mathbb{E}_{p(\mathbf{x}|y=+1)} \left[ \ell(f(\mathbf{x})) \right] + (1 - \pi) \mathbb{E}_{p(\mathbf{x}|y=-1)} \left[ \ell(-f(\mathbf{x})) \right]$$

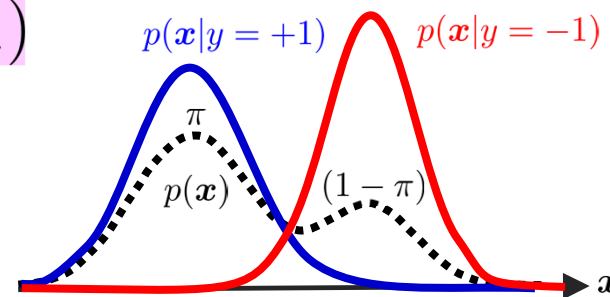
■ Use “U-density is mixture of P- and N-densities”:

$$p(\mathbf{x}) = \pi p(\mathbf{x}|y = +1) + (1 - \pi) p(\mathbf{x}|y = -1)$$

• Then

$$\pi = p(y = +1)$$

$$R(f) = \pi \mathbb{E}_{p(\mathbf{x}|y=+1)} \left[ \ell(f(\mathbf{x})) \right]$$



$$+ \mathbb{E}_{p(\mathbf{x})} \left[ \ell(-f(\mathbf{x})) \right] - \pi \mathbb{E}_{p(\mathbf{x}|y=+1)} \left[ \ell(-f(\mathbf{x})) \right]$$

• Empirical risk minimization (ERM) is possible from PU data, just by replacing expectations by sample averages!

$$R(\hat{f}_{\text{PU}}) - R(f^*) \leq C(\delta) \left( \frac{2\pi}{\sqrt{n_{\text{P}}}} + \frac{1}{\sqrt{n_{\text{U}}}} \right)$$

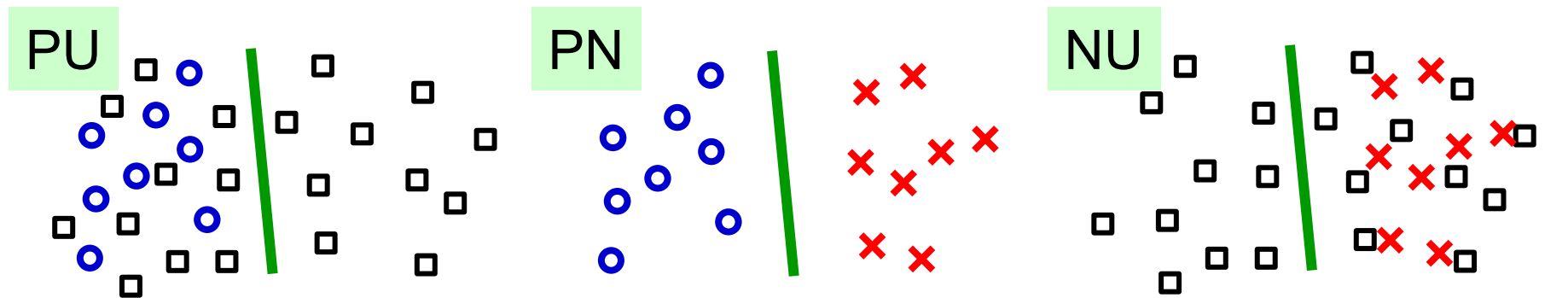
# (2-2) PNU Classification (Semi-Supervised Classification)

Sakai, du Plessis, Niu & Sugiyama (ICML2017)  
Sakai, Niu & Sugiyama (MLJ2018)

## Let's decompose PNU into PU, PN, and NU:

- Each is solvable.
- Let's combine them!

## Without cluster assumptions, PN classifiers are trainable!



$$R_{0/1}(f) \leq 2\hat{R}_{\text{PN+PU}}^\gamma(f) + \mathcal{O}(1/\sqrt{n_P} + 1/\sqrt{n_N} + 1/\sqrt{n_U})$$



# (2-3) Pconf Classification

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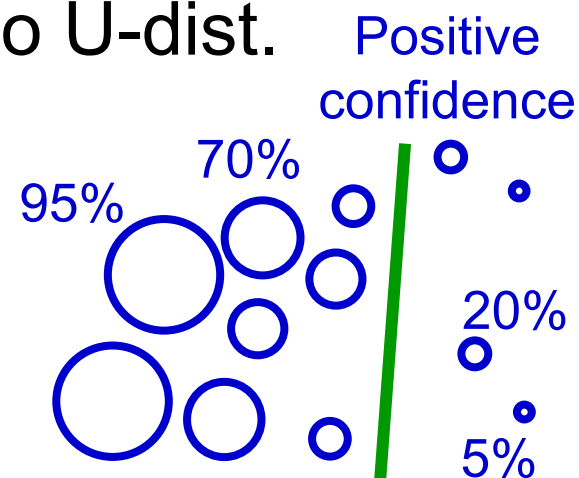
Ishida, Niu & Sugiyama (NeurIPS2018)

- Only P data is available, even not U data:
  - Data from rival companies cannot be obtained.
  - Only positive results are reported (publication bias).
- “Only-P learning” is unsupervised.
- From positive-confidence data, ERM is possible!
  - Augment r-Pconf samples to (1-r)-Nconf samples.
  - Importance sampling from P-dist. to U-dist.

$$R(f) = \pi \mathbb{E}_{p(\mathbf{x}|y=+1)} \left[ \ell(f(\mathbf{x})) + \frac{1 - r(\mathbf{x})}{r(\mathbf{x})} \ell(-f(\mathbf{x})) \right]$$

$$\pi = p(y = +1) \quad r(\mathbf{x}) = P(y = +1|\mathbf{x})$$

$$R(f^*) - R(\hat{f}) = \mathcal{O}_p(1/\sqrt{n})$$

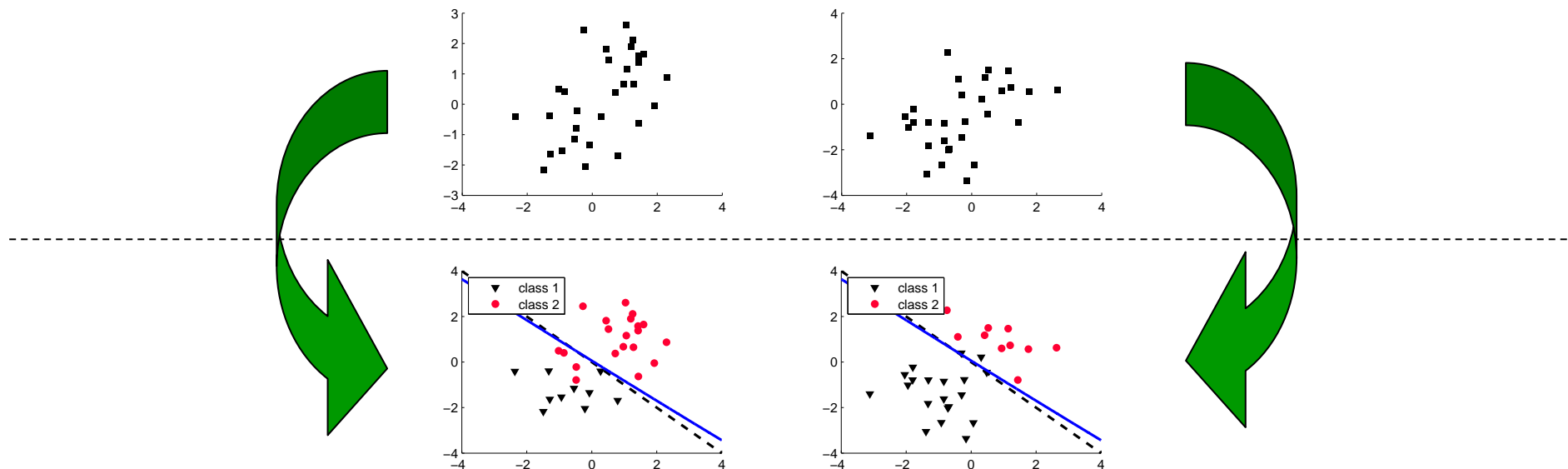


# (2-4) UU Classification

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du Plessis, Niu & Sugiyama (TAAI2013)  
Lu, Niu, Menon & Sugiyama (ICLR2019)  
Charoenphakdee, Lee & Sugiyama (ICML2019)  
Lu, Zhang, Niu & Sugiyama (AISTATS2020)

- From two sets of unlabeled data with different class priors, PN classifiers are trainable by ERM!



- In PU, we regarded U as noisy N.
- In UU, we use noisy P and noisy N!

$$\mathcal{O}_p\left(1/\sqrt{n}\right)$$

# (2-5) SU Classification

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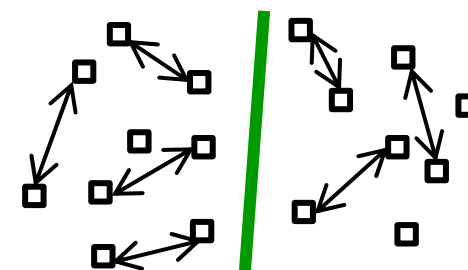
Bao, Niu & Sugiyama (ICML2018)

## ■ Delicate classification (money, religion...):

- Highly hesitant to directly answer questions.
- Less reluctant to just say “**same as him/her**”.

## ■ From similar data pairs and unlabeled data, PN classifiers are trainable!

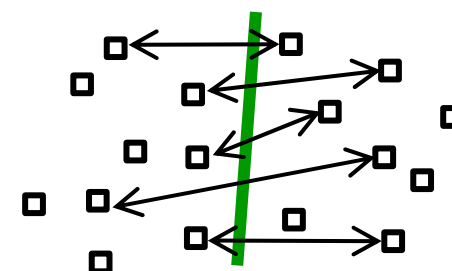
$$1/\sqrt{n}$$



- Decoupling S-pairs results in UU classification!

## ■ Learning from dissimilar data pairs is also possible.

- SDU classification is also possible.



Shimada, Bao, Sato & Sugiyama (NeCo2021)  
Dan, Bao & Sugiyama (arXiv2020)

# (2-6) Complementary Classification 44

Ishida, Niu & Sugiyama (NIPS2017)  
Ishida, Niu, Menon & Sugiyama (ICML2019)  
Chou, Niu, Lin & Sugiyama (ICML2020)

## ■ Labeling patterns in **multi-class** problems:

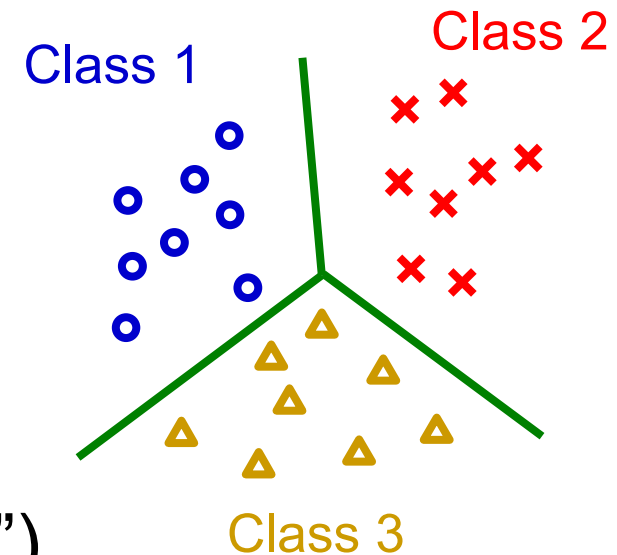
- Selecting the correct class from a long class list is extremely painful.

## ■ **Complementary labels**:

- Specify a class that a pattern does **not** belong to (“not class 1”).
- This is much easier and faster to collect!

## ■ **From complementary labels, classifiers are trainable by ERM!**

- Noisy labels with uniform transition to other classes.



$$1/\sqrt{n}$$

# Incorporating Ordinary Labels

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- Convert **multiclass labeling** into **yes-no labeling**:



[http://www.softbank.jp/corp/group/sbr/news/press/2014/20141029\\_01/](http://www.softbank.jp/corp/group/sbr/news/press/2014/20141029_01/)



<https://www.bostondynamics.com/atlas>

Is this Softbank Pepper?  
**Yes! (ordinary label)**

Is this iRobot Roomba?  
**No! (complementary label)**

- Use both of ordinary and complementary labels!**

$$R(f) = \mathbb{E}_{p(\mathbf{x}, y)} \left[ \mathcal{L}(f(\mathbf{x}), y) \right] + \left\{ (c - 1) \mathbb{E}_{\bar{p}(\mathbf{x}, \bar{y})} \left[ \bar{\mathcal{L}}(f(\mathbf{x}), \bar{y}) \right] + \text{Const.} \right\}$$

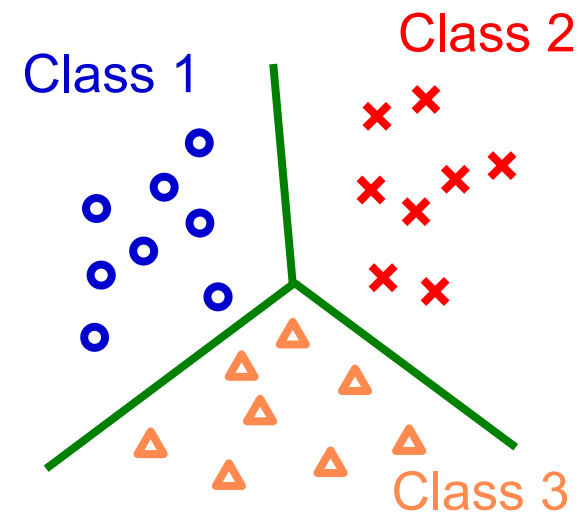
# (2-7) Partial-Label Classification <sup>46</sup>

## ■ **Partial label:** Nguyen and Caruana (KDD2008)

a subset of labels containing the true one

- “Either 1 or 2”
- Cheaper than ordinary labels

## ■ From partial labels, classifiers are trainable by ERM!

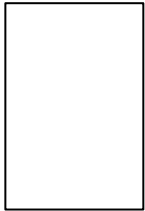
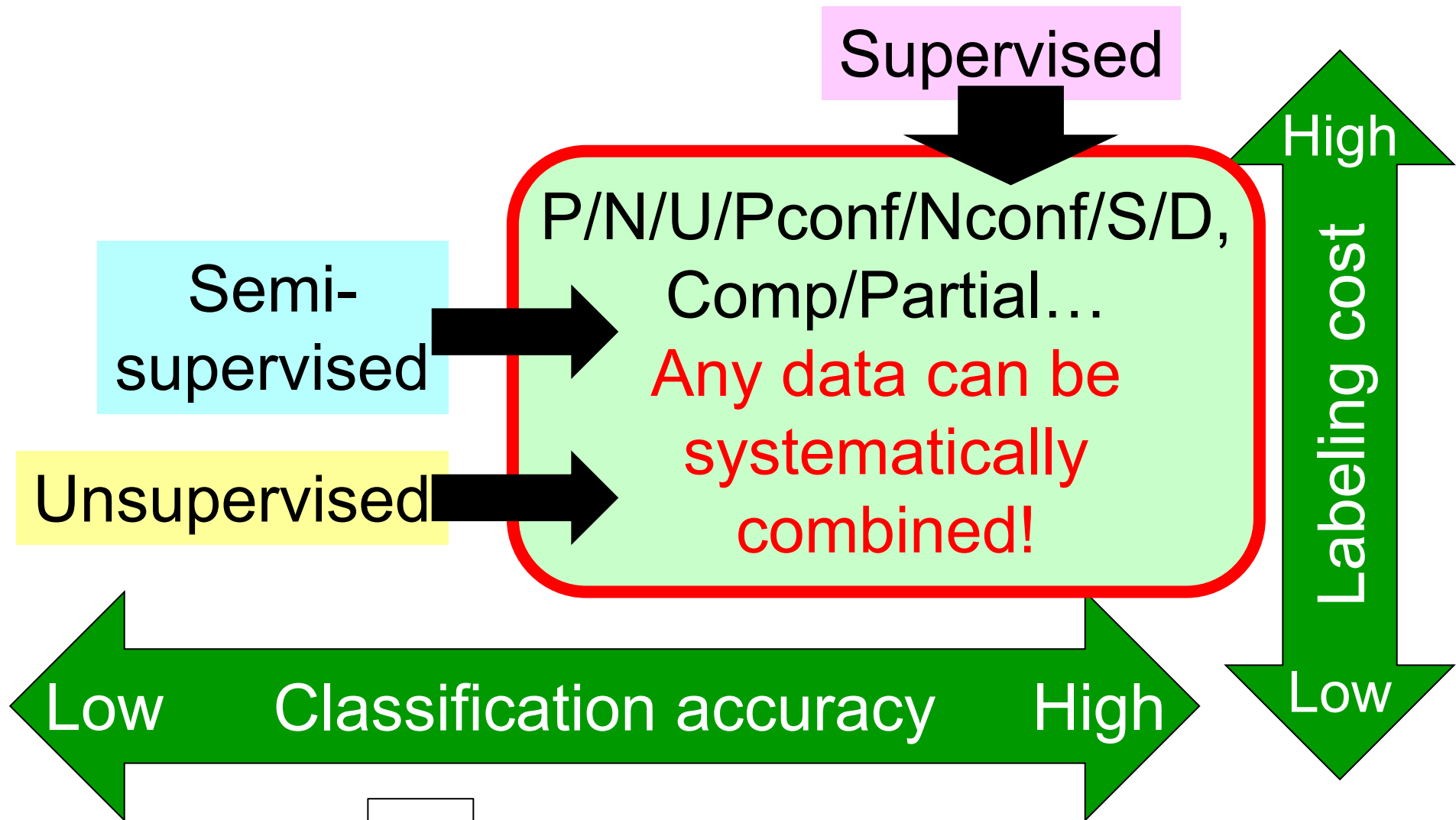


Feng, Kaneko, Han, Niu, An & Sugiyama (ICML2020)  
Lv, Xu, Feng, Niu, Geng & Sugiyama (ICML2020)  
Feng, Lv, Han, Xu, Niu, Geng, An & Sugiyama (NeurIPS2020)

- Complementary label is equivalent to partial label with size  $k-1$ .

# Weakly Supervised Learning

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Sugiyama, Ishida, Lu, Bao, Sakai & Niu,  
Machine Learning from Weak Supervision  
MIT Press, 2021(?)